

Product data sheet

Specifications



enclosed variable speed drive ATV61 Plus - 1400 kW - 400V - IP54

ATV61EXA5M14N4

⚠ To be discontinued on: 31 December 2023

⚠ To be end-of-service on: 31 December 2031

⚠ To be discontinued

Main

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|------------------------------|---|
| Range of product | Altivar 61 Plus |
| Product or component type | Variable speed drive |
| Device short name | ATV61 |
| Product destination | Synchronous motors Asynchronous motors |
| Product specific application | Pumping and ventilation machine |
| Assembly style | In floor-standing enclosure with separate air flows |
| Product composition | Control transformer for 230 V A plinth An IP65 remote mounting kit for graphic display terminal A switch and fast-acting fuses A wired ready-assembled Sarel Spacial 6000 enclosure Terminals/bars for motor connection Integrated drive system ATV61EM14N4E1 |
| EMC filter | Integrated |
| Network number of phases | 3 phases |
| Rated supply voltage | 380...415 V +/- 10 % |
| Supply frequency | 50...60 Hz |
| Motor power kW | 1400 kW, 3 phases at 380...415 V |
| Line current | 2344 A at 400 V3 phases / 1400 kW |
| IP degree of protection | IP54 |

Complementary

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| Apparent power | 1624 kVA for 400 V3 phases / 1400 kW |
| Prospective line Isc | 100 kA with external fuses |
| Continuous output current | 2430 A at 2.5 kHz, 400 V3 phases |
| Maximum transient current | 2916 A for 60 s 3 phases |
| Speed drive output frequency | 0.1...500 Hz |
| Nominal switching frequency | 2.5 kHz |
| Switching frequency | 2...4.9 kHz adjustable 2.5...4.9 kHz with derating factor |
| Speed range | 1...100 in open-loop mode, without speed feedback |

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| Speed accuracy | +/- 10 % of nominal slip 0.2 Tn to Tn without speed feedback |
| Torque accuracy | +/- 15 % in open-loop mode, without speed feedback |
| Transient overtorque | 120 % of nominal motor torque for 60 s 135 % of nominal motor torque for 2 s |
| Braking torque | 30 % without braking resistor <= 125 % with braking resistor |
| Asynchronous motor control profile | Voltage/frequency ratio, 5 points Voltage/frequency ratio, 2 points Flux vector control without sensor, standard Voltage/frequency ratio - Energy Saving, quadratic U/f |
| Synchronous motor control profile | Vector control without sensor, standard |
| Regulation loop | Adjustable PI regulator |
| Motor slip compensation | Suppressable Not available in voltage/frequency ratio (2 or 5 points) Automatic whatever the load Adjustable |
| Supply voltage limits | 342...457 V |
| Network frequency limits | 47.5...63 Hz |
| Overvoltage category | Class 3 conforming to EN 50178 |
| Local signalling | LCD display unit for operation function, status and configuration |
| Output voltage | <= supply voltage |
| Isolation | Electrical between power and control |
| Type of cable for external connection | IEC cable at 40 °C, copper 70 °C / PVC |
| Electrical connection | Terminal - 2.5 mm² / AWG 14 0.6 N.m (R1A, R1B, R1C, R2A, R2B) entry from the bottom Screw clamp terminals - 1.5 mm² 0.25 N.m (AI1-/AI1+, AI2, AO1, LI1...LI6, PWR) entry from the bottom Bar M12 - 16 x 240 mm² 41 N.m (L1/R, L2/S, L3/T) entry from the bottom at 6-pulse operation Bar M12 - 8 x 240 mm² 41 N.m (L1/R, L2/S, L3/T) entry from the bottom at 12-pulse operation |
| Motor recommended cable cross section | 9 (3 x 240) mm² 11 (3 x 185) mm² |
| Short-circuit protection | 3200 A fuse protection type gI - power supply upstream - at 6-pulse operation 1600 A fuse protection type gI - power supply upstream - at 12-pulse operation |
| Supply | External supply: 24 V (19...30 V)DC, <1 A Internal supply for reference potentiometer: 10 V (10...11 V)DC, <10 A Internal supply: 24 V (21...27 V)DC, <100 A |
| Analogue input number | 2 |
| Analogue input type | AI2 software-configurable voltage: 0...10 V DC, 24 V max, impedance: 30 kOhm, sampling time: 1.5...2.5 ms, resolution: 11 bits AI1-/AI1+ bipolar differential voltage: +/- 10 V DC, 24 V max, sampling time: 1.5...2.5 ms, resolution: 11 bits + sign AI2 software-configurable current: 0...20 mA/4...20 mA, impedance: 250 Ohm, sampling time: 1.5...2.5 ms, resolution: 11 bits |
| Analogue output number | 1 |
| Analogue output type | Software-configurable voltage: (AO1) 0...10 V DC - 500 Ohm - sampling time: 1.5...2.5 ms - resolution: 10 bits Software-configurable current: (AO1) 0...20 mA/4...20 mA - 500 Ohm - sampling time: 1.5...2.5 ms - resolution: 10 bits |
| Discrete output number | 2 |
| Discrete output type | Configurable relay logic: (R1A, R1B, R1C)NO/NC - 6.5...7.5 ms - 100000 cycles Configurable relay logic: (R2A, R2B)NO - 6.5...7.5 ms - 100000 cycles |
| Minimum switching current | 3 mA at 24 V DC (configurable relay logic) |
| Maximum switching current | 5 A at 250 V AC on resistive load - cos phi = 1 for configurable relay logic 5 A at 30 V DC on inductive load - L/R = 7 ms for configurable relay logic 5 A at 30 V DC on resistive load - L/R = 0 ms for configurable relay logic 5 A at 250 V AC on inductive load - cos phi = 0.4 for configurable relay logic |
| Discrete input number | 7 |
| Discrete input type | Programmable (LI1...LI5) at 24 V DC <= 30 V level 1 PLC 3.5 kOhm (duration=1.5...2.5 ms) Switch-configurable (LI6) at 24 V DC <= 30 V level 1 PLC 1.5 kOhm (duration=1.5...2.5 ms) Safety input (PWR) at 24 V DC <= 30 V 1.5 kOhm |

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| Discrete input logic | Positive (LI1...LI6), 0...5 V (state 0), 11...30 V (state 1) Negative (LI1...LI6), 16...30 V (state 0), 0...10 V (state 1) Positive (PWR), 0...2 V (state 0), 17...30 V (state 1) |
| Acceleration and deceleration ramps | S, U or customized Linear adjustable separately from 0.01 to 9000 s |
| Braking to standstill | By DC injection, <60 s |
| Protection type | Overheating protection: drive Thermal protection: drive Short-circuit between motor phases: drive Input phase breaks: drive Overcurrent between output phases and earth: drive Overvoltages on the DC bus: drive Break on the control circuit: drive Against exceeding limit speed: drive Line supply undervoltage: drive Line supply overvoltage: drive Against input phase loss: drive Thermal protection: motor Motor phase break: motor Power removal: drive Power removal: motor |
| Dielectric strength | 3535 V DC between earth and power terminals 5092 V DC between control and power terminals |
| Insulation resistance | > 1 mOhm 500 V DC for 1 minute |
| Frequency resolution | Display unit: 0.1 Hz Analog input: 0.024/50 Hz |
| Communication port protocol | Modbus CANopen |
| Connector type | 1 RJ45 (on front face) for Modbus 1 RJ45 (on terminal) for Modbus Male SUB-D 9 on RJ45 for CANopen |
| Physical interface | 2-wire RS 485 for Modbus |
| Transmission frame | RTU for Modbus |
| Transmission rate | 9600 bps, 19200 bps for Modbus on front face 4800 bps, 9600 bps, 19200 bps, 38.4 Kbps for Modbus on terminal 20 kbps, 50 kbps, 125 kbps, 250 kbps, 500 kbps, 1 Mbps for CANopen |
| Data format | 8 bits, 1 stop, even parity for Modbus on front face 8 bits, odd even or no configurable parity for Modbus on terminal |
| Type of polarization | No impedance for Modbus |
| Number of addresses | 1...247 for Modbus 1...127 for CANopen |
| Method of access | Slave CANopen |
| Options for enclosure configuration | Safe standstill for power circuit PTC relay for power circuit Pt100 relay for power circuit Insulation monitoring for power circuit Design for IT networks for power circuit External 230 V supply terminals for power circuit Buffer voltage 24 V DC power supply for power circuit Enclosure lighting for power circuit Key switch (local/remote) for power circuit Motor heating for power circuit External motor fan for power circuit Voltmeter for power circuit Door handle for main switch for power circuit Line contactor for power circuit 12-pulse supply for power circuit Ammeter for power circuit Enclosure heating for power circuit Motor choke for power circuit Cable entry via the top for power circuit Enclosure plinth for power circuit Relay output C/O for control circuit External 24 V DC supply terminals for power circuit Circuit breaker for power circuit Line reactor for power circuit Control terminals for control circuit Adaptor for 115 V logic inputs for control circuit Isolated amplifier for control circuit |
| Option card | Communication card for Modbus TCP/IP Communication card for Fipio Communication card for Modbus/Uni-Telway Communication card for Modbus Plus Communication card for EtherNet/IP |

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| | Communication card for DeviceNet Communication card for Profibus DP Communication card for Profibus DP V1 Communication card for Interbus-S Communication card for CC-Link Communication card for LonWorks Communication card for METASYS N2 Communication card for APOGEE FLN Communication card for BACnet Basic I/O extension card Extended I/O extension card Controller inside programmable card Multi-pump card Encoder interface cards |
| Operating position | Vertical +/- 10 degree |
| Colour of enclosure | Light grey (RAL 7035) |
| Colour of base of enclosure | Dark grey (RAL 7022) |
| Width | 3400 mm |
| Height | 2009 mm |
| Depth | 642 mm |
| Net weight | 1925 kg |

Environment

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|---------------------------------------|---|
| Electromagnetic compatibility | Electrostatic discharge immunity test level 3 conforming to IEC 61000-4-2 Radiated radio-frequency electromagnetic field immunity test level 3 conforming to IEC 61000-4-3 Electrical fast transient/burst immunity test level 4 conforming to IEC 61000-4-4 Conducted radio-frequency immunity test level 3 conforming to IEC 61000-4-6 1.2/50 µs - 8/20 µs surge immunity test level 3 conforming to IEC 61000-4-5 Voltage dips and interruptions immunity test conforming to IEC 61000-4-11 |
| Standards | EN/IEC 61800-5-1 EN 61800-3 environments 1 category C3 EN/IEC 61800-3 EN 61800-3 environments 2 category C3 EN 55011 class A group 2 |
| Product certifications | GOST ATEX |
| Marking | CE |
| Pollution degree | 3 conforming to EN/IEC 61800-5-1 |
| Noise level | 79 dB |
| Vibration resistance | 1.5 mm (f= 3...10 Hz) conforming to EN/IEC 60068-2-6 0.6 gn (f= 10...200 Hz) conforming to EN/IEC 60068-2-6 3M3 conforming to EN/IEC 60721-3-3 |
| Shock resistance | 4 gn for 11 ms conforming to EN/IEC 60068-2-27 3M2 conforming to EN/IEC 60721-3-3 |
| Environmental characteristic | 3C2 without condensation conforming to IEC 60721-3-3 3S2 without condensation conforming to IEC 60721-3-3 3K3 without condensation conforming to IEC 60721-3-3 |
| Relative humidity | 0...95 % |
| Ambient air temperature for operation | 0...40 °C (without derating) 40...50 °C (with current derating 1.5 % per °C) |
| Ambient air temperature for storage | -25...70 °C |
| Volume of cooling air | 11000 m3/h |
| Operating altitude | <= 1000 m without derating 1000...3000 m with current derating 1 % per 100 m |

Packing Units

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|------------------------------|----------|
| Unit Type of Package 1 | PCE |
| Number of Units in Package 1 | 1 |
| Package 1 Height | 200.0 cm |

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|------------------------------|-----------|
| Package 1 Width | 66.0 cm |
| Package 1 Length | 344.0 cm |
| Package 1 Weight | 1920.0 kg |
| Unit Type of Package 2 | CAR |
| Number of Units in Package 2 | 1 |
| Package 2 Height | 215.0 cm |
| Package 2 Width | 68.0 cm |
| Package 2 Length | 346.0 cm |
| Package 2 Weight | 1920.0 kg |

Contractual warranty

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| Warranty | 18 months |
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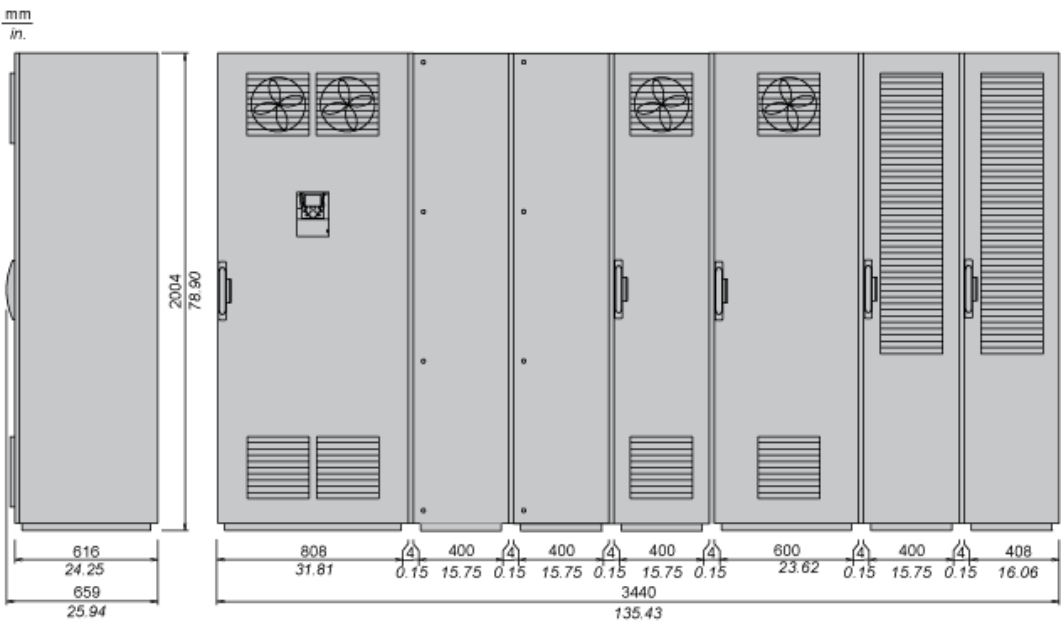
Product data sheet

Dimensions Drawings

ATV61EXA5M14N4

IP 23 Floor-Standing Enclosure with Separate Air Flows

Dimensions



NOTE: For each floor-standing enclosure added, allow a 4 mm/0.15 in. space for the seal.

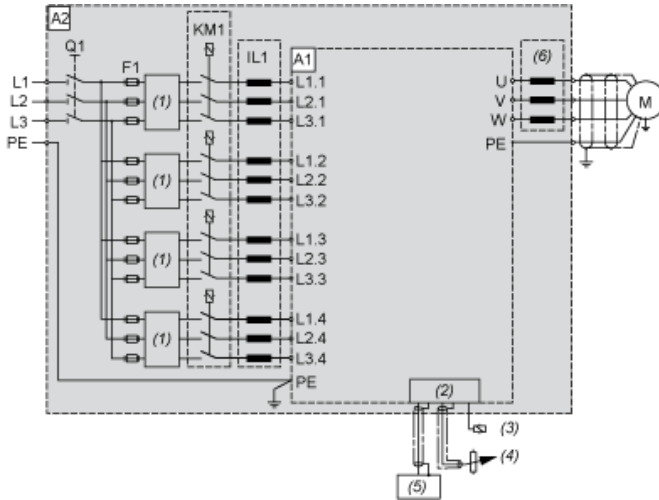
Product data sheet

Connections and Schema

ATV61EXA5M14N4

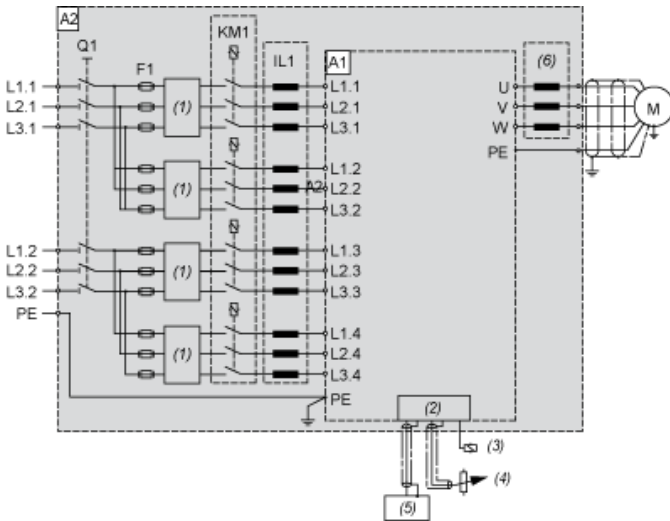
Floor-Standing Enclosure with Separate Air Flows

Standard 6-pulse Design



- | | |
|------------|-------------------------|
| A1 | Drive |
| A2 | Enclosure |
| F1 | Fuses |
| IL1 | Optional line choke |
| KM1 | Optional line contactor |
| M | Motor |
| Q1 | Switch |
| (1) | Filter |
| (2) | Control |
| (3) | Relay control |
| (4) | Reference potentiometer |
| (5) | PLC |
| (6) | Optional motor choke |

Optional 12-pulse Design



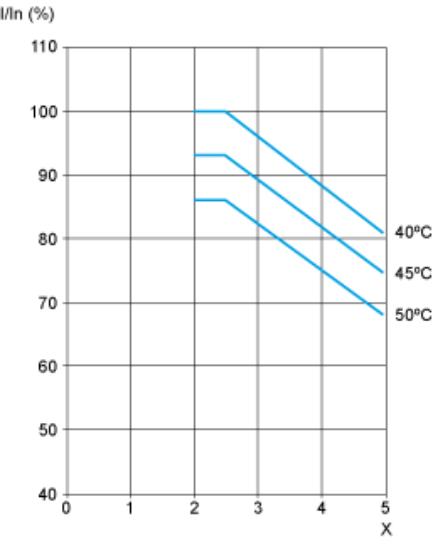
- | | |
|------------|-------------------------|
| A1 | Drive |
| A2 | Enclosure |
| F1 | Fuses |
| IL1 | Optional line choke |
| KM1 | Optional line contactor |
| M | Motor |
| Q1 | Switch |
| (1) | Filter |
| (2) | Control |
| (3) | Relay control |
| (4) | Reference potentiometer |
| (5) | PLC |
| (6) | Optional motor choke |

IP 23 Floor-Standing Enclosure with Separate Air Flows

Derating Curves

The derating curves for the drive nominal current (In) are dependent on the temperature and switching frequency. For intermediate temperatures, interpolate between 2 curves.

NOTE: The drive will reduce the switching frequency automatically in the event of excessive temperature rise.



X Switching frequency (kHz)

NOTE: The temperatures shown correspond to the temperature of the air entering the enclosure.

Recommended replacement(s)